

Session 22 – Sensors and Integration

A 2-in-1 Temperature and Humidity Sensor Achieving 62 fJ·K² and 0.83 pJ·(%RH)²

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Relative humidity and temperature (RH/T) monitoring applications:



Need: distributed Internet-of-things (IoT) environmental sensors



iiii CICC

Motivation: IoT Applications



Desired features:

- Low energy/measurement
- High sensitivity
- Monolithic and low-cost
- Wide supply range and supply insensitive



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Transducers Selection: Temperature



K. A. Makinwa, "Smart temperature sensor survey", 2010 to date.





Transducers Selection: RH



Mechanism:

- Interdigitated top layer metal
- Gaps filled with polyimide (PI)
- ε_{PI} ∝ RH
- Metal-PI-metal capacitance < RH
 Benefit:

CMOS compatible + fully integrated

Farahani et al. Humidity Sensors Principle, Mechanism, and Fabrication Technologies: A Comprehensive Review, *Sensors*, 2014







Prior RH/T Sensors



Example:

Sharp-QM1H0P00, ADI-AD7747, TI-HDC2080, ST-HTS221, TE-HTU21, etc.

- Widely used in commercial products
- Require *two distinct AFEs* that need extra
 - Power
 - Area
 - Complexity





Proposed RH/T Sensor Architecture



- Monolithic, CMOS-compatible transducers
- Require only one unified AFE that saves
 - Power
 - Area
 - Complexity





Proposed RH/T Sensor Architecture



- Monolithic, CMOS-compatible transducers
- Require only one unified AFE that saves
 - Power
 - Area
 - Complexity
- Closed-loop *R*&*C*-to-*T* conversion →
 High linearity & *robustness*
- Incomplete-settling SC-based WhB → High sensitivity & energy efficiency





Prior RC-Based Front-Ends

RC band-pass-filter-based



[P. Park, JSSC, 2015] [S. Pan, ISSCC, 2017] [W. Choi, ISSCC, 2018] [S. Pan, ISSCC, 2019]

Problems:

- C_{parasitic} degrades the sensitivity
- Sensitive to in-band supply noise
- $4 \times C V^2 f$ power due to the I/Q generation
- Need multiple matched components





Prior RC-Based Front-Ends

Switched-capacitor-based I



Switched-capacitor-based II



[R. Yang, High resolution CDC, JSSC, 2017]

[T. Jang, Low-power timer, ISSCC, 2016]

Problems:

- Need active drivers (LDOs or high-bandwidth, low-output-impedance OpAmp) and reference voltages → extra power overhead
- Extra noise sources





Revisit the SC-Resistor



Assuming C is fully charged to $V_{\rm s}$ & fully discharged to ground

Problem:

Need a voltage source (i.e., low impedance) as a SC driver

 \rightarrow prior work uses either LDO or active integrator (virtual ground)

Can we avoid the SC driver at the cost of incomplete-settling?





Incomplete-Settling SC-Based WhB



Q1: Assuming $R_1 = R_2$, is f = 1/RC when the bridge is balanced $(V_{A,mean} = V_B)$? *A1*: No. $f = \frac{1+e}{e} \frac{D}{RC} \approx \frac{0.684}{RC}$, assuming 50% duty-cycle

Q2: Why do I care if $f \neq 1/RC$?

A2: Because the error is hard to calibrate:

- Not constant, but depends on duty-cycle
- Highly sensitive to $C_{\text{parasitic}}$ at node A





Proposed Incomplete-Settling SC-Based WhB



C_f minimizes the incomplete-settling error

Proposed Incomplete-Settling SC-Based WhB



Benefits:

- Integrate *R*-transducer & *C*-transducer
- Reduce the settling error by \sim 5200× (choosing $C_{\rm f} = 60C$) at no static power cost
- Insensitive to C_{parasitic} & switching imperfections
- High sensitivity & inherent supply rejection
- Low swing → relax readout circuit linearity requirement
- $R_1 \& R_2$ branch costs little power & area







WhB front-end:

- Two SC cells in time-multiplexed fashion
- $R_1 = R_2$ ensures the maximum sensitivity





Active loop LPF:

- Chopping removes 1/f noise & offset
- Clock divider \rightarrow 8× lower g_m -cell BW & power





- VCO & TDC:
- A VCO closes the FLL $\rightarrow f = 1/RC$ w/ high loop gain
- A TDC samples the VCO phases & achieves 1st order noise-shaping





- Temp. mode: $T_{\text{Temp}} = R$
- RH mode: $T_{\rm RH} = RC_{\rm RH}$
- Temperature effect on RH can be removed by correlating the two results



Chopper-Stabilized Active Filter



- Choose g_m-C over closed-loop options due to
 - High energy efficiency
 - Relaxed linearity requirement
- Telescopic + chopping → >80dB gain over PVT & 2.4 noise efficiency factor
- Down-converting at cascode-nodes → ~100× lower impedance & higher bandwidth





- VCO noise attenuated by active filter gain
- $1-z^1$ restores the *f*-to-phase integration & shapes the quantization noise
- 2MHz sampling rate (OSR=1000) \rightarrow 116dB SQNR



System Linearity Verification



- Simulated w/ ideal R & C
- >92dB loop gain over PVT
- <±10ppm linearity error from -40°C to 85°C

FLL provides 16-b RC-to-T linearity across industrial temperature range



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Implementation



Power breakdown (µW)



- Implemented in TSMC 180nm process
- Active area: 0.72mm² (RH transducer: 0.21mm²)
- Power consumption: 15.6µW @ 1.5V (RT)





Measurements: FLL & TDC



- FLL RMS jitter: 17ps @RT
- TDC bitstream shows 20dB/dec. noise shaping



Measurements: Resolution vs. Time



- Resolution was measured at 300K & 35%RH
- Normalized to temperature and RH inputs
- 2mK temperature resolution & 0.0073%RH humidity resolution achieved in 1ms





Measurements: Mode Switching Transient



- FLL settles in 0.6ms to re-balance the WhB
- $V_{\rm A}$ settles back to $V_{\rm DD}/2$
- VCO settles to a different operating point





Measurements: Temp. Transfer Curve & Error



- 1st order calibration; no high-order polynomial fit due to FLL's high linearity
- 3σ error: 0.55K in the industrial temperature range





Measurements: RH Transfer Curve & Error



- 1st order calibration; no high-order polynomial fit due to FLL's high linearity
- 3σ error: 2.2%RH from 10%RH ~ 95%RH (limited by instrumentation)





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Comparison w/ Prior Environmental Sensor

| | Parameter | P.Park JSSC'15 | S. Pan ISSCC'19 | S.Pan ISSCC'19 | W. Choi ISSCC'18 | Z. Tan JSSC'13 | S. Park VLSI'18 | Maruyama JSSC'18 | This Work |
|-----------------|--|-------------------|--------------------|-------------------|---------------------|-------------------|--------------------|---------------------|-----------|
| System | Sensor type | Temperature | | | | RH | | RH & Temperature | |
| | Tech. (nm) | 180 | 180 | 180 | 65 | 160 | 180 | 180 | 180 |
| | Active area (mm ²) | 0.09 | 0.12 | 0.12 | 0.007 | 0.28 | 2.7 | 4.5 | 0.72 |
| | Supply (V) | 1.7/1 | 1.6~2 | 1.6~2 | 0.85~1.05 | 1.2 | 1 | 1.55 | 1.5~2 |
| | Conversion time (ms) | 32 | 10 | 10 | 1 | 0.8 | 1.28 | 0.024 | 1 |
| | Power (µW) | 31 | 52 | 94 | 68 | 10.3 | 2.69 | 3875 | 15.6 |
| Temp. sensor | Temp. range (°C) | -40~85 | -40~180 | -55~125 | -40~85 | 25 only | N/A | -20~85 | -40~85 |
| | 3σ error (K) [trim points] | 0.12[3] | 0.1[2] | 0.14[2] | 0.7[2] | - | - | 0.6[NA] | 0.55[2] |
| | Resol. (mK) | 2.8 | 0.46 | 0.16 | 2.8 | - | - | 15 | 2 |
| | FOM(fJ·K ²) | 8,000 | 110 | 20 | 530 | - | - | 20,925 | 62 |
| RH sensor | RH range (%) | - | - | - | - | 30~95 | 30~90 | 0~100 | 10~95 |
| | 3σ error (%) [trim points] | - | - | - | - | >2[2] | 5.6[NA] | 4[NA] | 2.2[2] |
| | Resol. (%RH) | - | - | - | - | 0.05 | 0.038 | 0.0057 | 0.0073 |
| | FOM(pJ·%²) | - | - | - | - | 20.75 | 4.97 | 3.02 | 0.83 |
| IEE | IEEE CICC, Austin, TX, April 14-17, 2019 | | | | | | | | |



Conclusion

Target:

 A compact, energy-efficient & robust environmental sensor for IoT applications

<u>Techniques:</u>

- Incomplete-settling SC-based WhB → High sensitivity & low power
- FLL + noise-shaping TDC \rightarrow high linearity & high DR

<u>Results:</u>

- Fully integrated temperature & humidity sensor consisting of a unified R&C-to-D converter, achieving:
- 62fJ·K² & 0.83pJ ·(%RH)² FOMs normalized to temp. & RH
- 0.12K/V & 0.43%RH/V supply insensitivity





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